# IOI'04: Solution of *Polygon*

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# 1 Minkowski decomposition

#### 1.1 The setting

Although computing the Minkowski sum is straightforward ([2]), deciding whether a polygon is the Minkowski sum of 2 polygons is NP-complete.

There is a pseudo-polynomial time algorithm for the latter ([1]), which we now sketch. If the input is the sequence of N edges, then the input size is  $O(N(\log m + \log E))$ , where m is the maximum number of integer points on any edge, and E is the maximum absolute value of any coordinate defining a primitive edge vector, as defined below. The algorithm in [1] runs in O(tNm) time, where  $t = |P \cap \mathbb{Z}^2|$ .

# 1.2 Solution of the IOI-04 problem *Polygon*

We call the input polygon P. Suppose that it consists of N vertices with non-negative coordinates of the form  $v_i = (x_i, y_i), 0 \le i \le N - 1$ , given in counter-clockwise order.

**Definition 1.1** We call a vector v = (a, b) primitive, if gcd(a, b) = 1, where  $a, b \in \mathbb{Z}_{\geq 0}$ . Equivalently, v is primitive iff there are no integer points in its interior.

The edges of P are represented by the vectors  $E_i = v_i - v_{i-1} = (a_i, b_i), 1 \le i \le N$ , where  $a_i, b_i \in \mathbb{Z}$  and the indices are taken modulo N. Given an edge  $(a_i, b_i)$ , if  $n_i = \gcd(a_i, b_i)$ , then we consider the corresponding primitive edge  $e_i = (\frac{a_i}{n_i}, \frac{b_i}{n_i})$ . We call the sequence of vectors  $\{E_i\}_{1 \le i \le m} = \{n_i e_i\}_{1 \le i \le m}$  edge sequence of the polygon, where  $e_i$  is a primitive vector.

There is a crucial observations in computing the summands A, B such that P = A + B.

**Lemma 1.2** Every primitive edge of P must appear as an edge either of A or of B. If the edge is not primitive, there is a third possibility: that it is the Minkowski sum of an edge of A and an edge of B, where these edges are parallel.

Now we can deduce the following fact: A polygon is a summand of P iff its edge sequence is of the form  $\{k_j e_j\}_{j \in J}$ , where  $J \subseteq \{1, \dots N\}$ ,  $0 \le k_j \le n_j$ ,  $k_j \in \mathbb{Z}$  and  $\sum_{j \in J} k_j e_j = (0, 0)$ , i.e. the sum of the vectors that represent its edges is zero.

Below we present algorithms to find summands as required by the problem *Polygon*. In computing summand polygons, the chosen algorithm may produce a summand with one or more negative coordinates. In this case, we must shift both summands to non-negative coordinates. This is a valid operation, because shifting does not change any polygon.

#### 1.3 Looking for a segment summand

The polygon has a segment summand iff at least one pair of the (sub)vectors of its edge sequence has a zero vector sum. Based on this fact, we present 3 algorithms of increasing speed.

Our algorithms start with finding the primitive vectors for every edge, by performing a GCD computation (at section 1.6 there are two algorithms for the GCD computation). For polygons that contain only primitive edges, this step is unnecessary.

Naive First we compute the edges of the polygon. Every edge is of the form

$$E_i = (x_{i+1} - x_i, y_{i+1} - y_i) = (a_i, b_i)$$

where the indices are taken modulo N. Next we compute all the gcd's of form  $gcd(a_i, b_i)$  and we form the edge sequence using the primitive vectors as in the preamble. This computation can be done in O(mN) time, where  $m = \max n_i = \max gcd(a_i, b_i)$ .

For every vector in the sequence we compute its sum with every other vector in the sequence. This can be done in  $O(m^2N^2)$  total time.

Clever We compute the edge sequence as before in O(mN) time. We sort the sequence with respect to their x-coordinate, in  $O(mN \lg(mN))$  time.

For every vector in the sequence we test if another vector in the sequence with the opposite x-coordinate add to zero. We perform the searching by binary search, since the sequence is sorted, in  $O(\lg(mN))$  time. The total time is  $O(mN(\lg(mN)))$ .

**Advanced** We compute the edge sequence as before in O(mN) time. We insert the edges in a hash table, using as key value their x-coordinate. The insertion is performed in O(1).

For every edge in the sequence we search the hash table for another edge with opposite x-coordinate that add to zero. The search is performed in O(1). The total time is O(mN).

#### 1.4 Looking for a triangle summand

Naive We compute the edge sequence as before in O(mN) time. We can form all the possible triplets and test if they add to zero. The total time is  $O(m^3N^3)$ .

**Clever** We compute the edge sequence as before in O(mN) time and we sort it with respect to their x-coordinate in  $O(mN \lg(mN))$  time.

We form all the possible sums of two vectors in  $O(m^2N^2)$  time. For every such sum we search, using binary search in  $O(\lg(mN))$ , for another vector such that their sum is zero. The total time is  $O(m^2N^2\lg(mN))$ .

**Advanced** We compute the edge sequence as before in O(mN) time and we sort them in increasing order with respect to their x-coordinate in  $O(mN \lg(mN))$  time.

For every edge in the sequence, say k, scan the sequence from the left to find i and from the right to find j, such that  $E_k + E_i + E_j = 0$ . Because of the sorted order we can advance either i or j according to whether the sum  $E_k + E_i + E_j$  is positive or negative. The total time is  $O(m^2N^2)$ .

Alternatively we can insert the vectors in a hash table, using as a key their x-coordinate, and for every sum of 2 vectors we search for a vector in the hash table, in O(1), such that the sum of the three is zero. Again the total time is  $O(m^2N^2)$ .

### 1.5 Looking for a quad summand

Naive We compute the edge sequence as before in O(mN) time. We can form all the possible 4-tuples and test if they add to zero. The total time of the algorithm is  $O(m^4N^4)$ .

Clever We compute the edge sequence as before in O(mN) time. We can form all the possible triplets in  $O(m^3N^3)$ . For every triplet we search for a vector such that the sum of the four is zero.

If we have sorted the edges with respect to their x-coordinate and we do binary searching then the total time of the algorithm is  $O(m^3N^3 \lg(mN))$ .

If we insert the edges in a hash table, using their x-coordinate as key, we perform the search in O(1) time and so the total time of the algorithm is  $O(m^3N^3)$ .

Advanced We compute the edge sequence as before in O(mN) time. We form all the possible sums of 2 edges, in  $O(m^2N^2)$  time and we insert them in a hash table, using as key their x-coordinate. For every such sum we search the hash table for a vector such that the total sum is zero. The total time is  $O(m^2N^2)$ .

#### 1.6 Computation of the gcd

We present two algorithms that compute the gcd of two integers a, b. The first algorithm is the traditional Euclid algorithm, while the second one is the Binary gcd algorithm (see [3] at chapter 4).

#### **Algorithm 1** Euclid $\gcd(a,b)$

```
Require: a,b \in \mathbb{Z}

Ensure: y = \gcd(a,b)

if b = 0 then

RETURN a

else

RETURN Euclid_\gcd(b,a \mod b)

end if
```

### **Algorithm 2** Binary\_gcd(a, b)

```
Require: a, b \in \mathbb{Z}
Ensure: y = \gcd(a, b)
  g = 1
  while a is even AND b is even do
    a = a/2 (right shift)
    b = b/2
    g = 2 * g \text{ (left shift)}
  end while
  while u > 0 do
    if a is even then
      a = a/2
    else if b is even then
      b = b/2
    else
      t = |a - b|/2
    end if
    if a < b then
      b = t
    else
      a = t
    end if
  end while
  RETURN g * b
```

# References

- [1] S. Gao and A. Lauder, Decomposition of polytopes and Polynomials, Discrete and Computational Geometry 26 (2001), 501-520
- [2] L.J. Guibas and R. Seidel, Computing Convolutions by Reciprocal Search, Symposium of Computational Geometry, 2001
- [3] D. Knuth, The Art of Computer Programming, vol 2, Addison-Wesley, 3rd edition, 1998